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On the applicability of Persistent Scatterers interferometry (PSI) analysis for long term CO₂ storage monitoring

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Abstract

Persistent scatterers synthetic aperture radar interferometry (PSI) analysis is viewed as a promising monitoring technique for multiyear detection of ground surface displacements during long term CO₂ injection into deep aquifers (of the order of 25 to 50 years). This technique was successfully utilized at the CO₂ storage site of In-Salah (Algeria). Nevertheless, this success may not be generalized to future onshore industrial-scale CO₂ storage sites, which are planned in far more complex contexts mostly presenting natural terrains, either agricultural or vegetated areas, i.e. characterized by poor PS density, which might locally drop to zero, hence hampering the deployment of the PSI technique. The objective of the present paper is to discuss the constraints on the PSI application regarding the specificities (magnitude, spatial or temporal scales and evolution) of the deformation phenomenon associated with the CO₂ injection into storage aquifers. This discussion is supported by the estimates of the expected spatio-temporal evolution of surface vertical displacements caused by CO₂ injection in deep aquifers by combining the approximate solutions for pressure build-up and for the associated vertical displacements in an elastic half-

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space. A possible option to enhance the performance of the PSI technique is explored, namely the deployment of a network of corner reflectors CR corresponding to artificial devices installed on ground to complement the existing “natural” PS network. A methodology is then proposed to optimize the CR network (number and position) in an iterative strategy (e.g., every 10 years) relying on the prediction of surface deformation. The methodology is illustrated by a CO₂ injection scenario in the Paris basin context.

Keywords: CO₂ geological storage; Monitoring protocol; InSAR remote sensing; Persistent Scatterers; geomechanical model; Corner Reflectors.

Introduction

CO₂ capture and geological storage (denoted CCS) is seen as a promising technology in the portfolio of measures required to mitigate the effects of anthropogenic greenhouse gas emissions (IPCC, 2005). Among the available geological targets, deep aquifers are recognized to offer very large potential storage capacity with a broad distribution throughout the world in all sedimentary basins (e.g., IPCC, 2005). Therefore, the present paper will primarily focus on this option. The International Energy Agency (IEA) recently evaluated the contribution of CCS to emissions reductions by 2050 to one fifth in order to achieve the most cost-effective stabilisation of greenhouse gas concentrations (IEA, 2009). On this basis, the IEA concludes that the implementation of the technology should reach 100 projects in 2020, and more than 3000 in 2050 representing an amount of 10 Gt of CO₂ stored per year. These figures highlight the large number of storage sites that shall be operated. Nevertheless, a prerequisite to any CCS large scale industrial development is the demonstration that the storage is both efficient and safe as outlined by the European directive on geological storage of carbon dioxide

(directive 2009/31/EC, April 2009). In this context, monitoring techniques constitute a key component of any CO₂ storage risk management strategy aiming at providing information on the CO₂ fate (migration and trapping) within the reservoir and demonstrating that CO₂ containment is effective (e.g., Benson, 2006).

Among the possible monitoring techniques, the space-borne Differential SAR (Synthetic Aperture Radar) interferometry may constitute a promising and cost-effective option, as it can provide valuable information on surface deformation induced by volumetric changes through time and space resulting from CO₂ injection in deep aquifers (Tamburini et al., 2010). This technique uses the phase of the radar signal in order to derive an estimation of the displacement of the ground surface between two passes of the satellite over the area. Further details can be found for instance in Raucoules et al. (2007). The basic idea is that (once removed flat earth and topographic components) the phase difference is proportional (modulo 2π) to the Line of Sight displacement occurred between the two acquisitions (assuming that we can identify a stable reference area on the image. If not, the displacement is obtained with an unknown constant value offset). A major interest of the technique lies on the fact that the spatial sensor is able to image the ground surface regularly (presently, repetitiveness varies depending on characteristics of the available satellites between few days to more than one month).

Yet, one major limitation results from the temporal decorrelation phenomena (Zebker and Villasenor, 1992) stemming from changes in the physical (e.g. dielectric characteristics) or geometric (e.g. the distribution inside of the image elementary cell) characteristics of the backscattering objects. Multi-temporal processing of interferometric series is generally needed to cope with this shortcoming. Among the possible multi-temporal techniques, PSI (Persistent Scatterers Interferometry – e.g. Ferreti et al., 2000) are advanced techniques based on the processing of numerous, typically more than 30, images to identify a network of

71 persistent, temporally stable, highly reflective ground features -persistent scatterers (denoted
72 PS). These scatterers typically are cultural features of the developed landscape such as
73 buildings, utility poles, roadways, etc., but also natural stable elements with stable and strong
74 backscattering characteristics (such as stable rocks with specific orientation).

75 To date, such space-borne techniques have been successfully used in a variety of domains
76 involving subsurface fluid withdrawal / injection and surface deformation response, for
77 instance groundwater flow characterization in complex aquifers systems (Bell et al., 2008), oil
78 / gas fields characterization (e.g., Vasco et al., 2008a), monitoring of seasonal gas storage
79 (e.g., Teatini et al., 2011). More recently, surface deformation have been measured at In Salah
80 Gas Project in Algeria, where 0.5–1 million tonnes CO₂ per year have been injected over the
81 past 5 years (e.g. see site context described by Rutqvist et al., 2010). This analysis revealed an
82 average ground uplift of 5 mm/year and allowed getting better insight not only in the CO₂
83 migration at depth (e.g., Mathieson et al., 2009), but also in the behaviour of the storage
84 reservoir (e.g., Vasco et al., 2008b) and of the storage complex during injection operations
85 (e.g., Rutqvist et al., 2010).

86 However, such a successful result might not be easily generalised to any onshore CO₂ storage
87 sites, because the In Salah case is characterized by very favourable conditions for the
88 implementation of the PSI technique, the site being located in an arid region so that the
89 Permanent Scatterer PS density is very high, exceeding 1,000 per km² (300,000 PS used by
90 Tamburini et al., 2010 over an area of approximately 10 km by 15 km).

91 The objective of the present paper is to get a better insight in the applicability of the Persistent
92 Scatterers Interferometry implementation regarding the conditions of the future storage sites
93 and the specificities of the expected ground deformation phenomenon, i.e. the expected
94 spatio-temporal evolution of surface displacements caused by CO₂ injection operations at
95 depth.

The remainder of the paper is organized as follows. We estimate in a first section the expected surface displacements by means of an analytical model. Though inherently based on simplifications, the analytical results allow investigating a large variety of injection scenarios (e.g. depth, injection rate, storage aquifer characteristics, etc.) useful to support the discussion in section 2. Given the discussed limitations for the CO₂ storage context, we propose to explore, in a third section, a possible strategy to enhance the performance of the PSI technique for CO₂ storage monitoring by deploying a network of “artificial” PS, i.e. corner reflectors CR (e.g., Novali et al., 2005) in an iterative design approach over the whole injection duration.

1. Estimates of the expected spatio-temporal evolution ground vertical displacements

In this section, we briefly describe an analytical solution for assessing ground displacement assessment during CO₂ injection in deep aquifers (section 1.1). Details of the analytical model are provided in Appendix A and B. This model is then applied to a typical injection scenario (section 1.2) and its applicability is discussed (section 1.3).

1.1. Analytical solution for ground displacement assessment

In the present article, the expected spatio-temporal evolution of ground vertical displacements due to CO₂ injection at depth are estimated using an analytical model developed by combining :

- the approximate solutions for pressure build-up (i.e. the pressure increase due to injection) during CO₂ injection in brine aquifers of very large spatial extent (seen as open systems) based on the studies of Mathias et al. (2009a&b);

- the poro-elastic solution for vertical surface displacements estimate in an elastic half-space, originally developed in the field of hydrocarbon and geothermal activities by considering an axi-symmetric thin disk reservoir with general reservoir pressure distribution (Segall, 1992; Segall and Fitzgerald, 1998).

For sake of clarity, the main assumptions and formulations of both analytical solutions are respectively described in Appendix A and B. Noteworthy, each of these solutions have been validated through numerical simulations (Mathias et al., 2009a) or against in situ observations (at Lacq in southern France, see Segall, 1992).

1.2. Analysis of a typical injection scenario

We assess the spatio-temporal evolution of ground vertical displacements resulting from a typical scenario corresponding to 1 Mt/y CO₂ injection during 25 years into a saline aquifer formation at 1500m depth. Considering a pressure and geothermal gradient of respectively 4×10^5 Pa/m and 0.03 °C/m, the initial pressure and temperature are of 15 MPa and 45 °C at 1500m depth. The homogeneous properties of the aquifer formation are typical of sedimentary formations suitable for CO₂ storage, with high-enough permeability and porosity (see for instance Birkholzer et al., 2009 for typical hydrogeological properties and Rohmer and Seyed, 2010 for typical geomechanical properties) and are summarized in Table 1.

[Table 1 about here]

Figure 1 depicts the spatial distribution of changes in vertical ground displacements estimated using the equations described in Appendix A and B. Different injection durations are considered and vary from 1 month to 25 years. The pressure build-up reaches a maximum value within the injector near-zone and decreases deeply in an exponential fashion within the CO₂ plume region (the extent being marked by the steep decrease of the pressure build-up in

Figure 1A) and linearly within the brine-filled region. The vertical surface displacements follow the same trend (Figure 1B), but with a smoother form of the spatial distribution so that these are approximately constant over approximately 1 km and steeply decrease reaching (and even exceeding) the lateral extent of the pressurized zone at depth (i.e. the zone for which the pressure build-up is non-nil). For instance, after 2 years of injection, the vertical surface displacements exceed 4 mm over the lateral distance range of 0 to 1 km and decrease reaching ~10 km given that the extent of the pressurized zone reaches ~8 km. The smooth spatial distribution is explained by cumulative contribution of all the rings of dilation with magnitude proportional to the pressure build-up (i.e. decreasing with the lateral distance) as shown in Appendix (Figure 9).

Let us consider the gradient (in absolute value) of displacements corresponding to the difference between vertical displacements respectively observed at positions $\vec{r}$ and of $\vec{r} + \vec{\Delta}$ divided by the distance $\|\vec{\Delta}\|$, where $\|\vec{\Delta}\|$ is the characteristic length of a satellite image pixel (typically between 10 and 50 m depending on sensor and processing). This gradient is largely smaller than the maximum allowed value corresponding to half a fringe per pixel, *i.e.* of about $1.5 \text{ cm}/10\text{m}=1.5 \times 10^{-3}$ to $1.5\text{cm}/50\text{m}=3 \cdot 10^{-4}$ for vertical movements with ERS data (Raucoules et al., 2007). This value would be modified for sensors with different resolutions and wavelengths, the maximum measurable gradient being proportional to wavelength and inversely proportional to pixel size. Even in case of a point-based method (such as PSI techniques) with larger $\|\vec{\Delta}\|$, typically ranging 500m to 1000m in rural zones (in this case $\|\vec{\Delta}\|$ does not correspond to the pixel size, but to the distance between PS), this maximum measurable gradient should not be theoretically a limitation, because the expected total deformation of the order of ~1 cm, as shown in Figure 1B, corresponds to less than one C-band sensor fringe (equivalent to ~3 cm of vertical displacement).

[Figure 1 about here]

Considering the temporal evolution of the maximal surface displacement within the injector near-zone, Figure 2 shows that it reaches a maximum value of ~11 mm over a time span of 25 years and evolves following a logarithmical function over time. This trend is partly explained by the temporal evolution of the maximum pressure build-up within the injector near-zone. But, given its rapid evolution (after 1 month of injection, it reaches more than 85 % of the maximal pressure build-up), the temporal evolution is in great part explained by the cumulative contributions of rings of dilation, as shown in Figure 9, (Appendix A), whose number increases over time as the pressure front propagates within the aquifer formation.

[Figure 2 about here]

1.3. Applicability of the analytical solution

The described analytical model is proposed as a quick-assessment tool, which should be used to capture the general trend of surface deformation due to CO₂ injection, i.e. to estimate orders of magnitude of the expected vertical displacements either to assess the likelihood of a risk event associated with ground surface perturbations in a preliminary risk analysis of the storage site (e.g., Bouc et al., 2011), or, as proposed in the present paper (section 2 & 3), to investigate the applicability of the PSI analysis considering a broad range of different scenarios. Noteworthy, the application of the model to the In-Salah's case considering rock properties and injection scenario described by Vasco et al. (2010) produces a measurable surface displacement of approximately 4 mm/y, i.e. in the order of what has been actually measured.

An in-depth understanding of the surface deformation process due to CO₂ injection at depth should consider several aspects, which the analytical model hardly accounts for, most of them being related to the complexity of both the deformation processes and the geological subsurface structure.

The described model assumes poro-elastic rock behaviour, hence implying that uplift instantaneously follows linearly the reservoir volumetric increase. Though confirmed through in situ compaction measurements (see e.g. the Groningen field, studied by Mobach and Gussinklo, 1994), a nonlinear dependence may also appear in some cases. See detailed discussion by Hettema et al. (2002). Furthermore, the ground deformation processes may be complicated by the presence of soils and unconsolidated rocks near the surface (e.g., Singh, 1992).

The proposed model considers an idealized view of the subsurface structure so that both the reservoir and the surrounding rock are considered homogeneous and having the same material properties. Yet, aquifer formations targeted for CO₂ storage are mostly located within large sedimentary basins, which can be viewed as multi-layered systems (see e.g., Birkholzer et al., 2009). Analytical models have been proposed to account for this aspect (Fokker and Orlic, 2006) and can be extended as a future direction of research to the CO₂ storage case in the similar approach as proposed in section 1. Furthermore, the presence of geologic discontinuities (i.e. the existence of faults) may increase ground movement potential, but on a localized spatial scale, as numerically demonstrated by Rutqvist et al., (2010).

2. Constraints on the implementation of PSI technique

In turn, we examine constraints to the implementation of the PSI technique regarding the specificities of the deformation phenomenon associated with the CO₂ injection at depth, in terms of magnitude (section 2.1), spatial and temporal scales (section 2.2 and 2.3) and evolution (section 2.4). Table 2 summarizes the constraints on the PSI implementation and the needs in terms of sensor characteristics in order to address the issues resulting from the expected motion characteristics.

[Table 2 about here]

2.1. Magnitude of the deformation

It is difficult to determine beforehand whether the specific deformation phenomenon associated with the CO₂ injection at depth (as illustrated by the typical injection scenario described in section 1.3), may be monitored, because the feasibility and accuracy of PSI strongly depend on the number of satellite acquisitions and the temporal baselines (e.g. Hanssen, 2005).

The value of the precision PSI techniques has been widely discussed in the literature and can vary from less than 1 mm to centimeters. Colesanti et al. (2003) suggested that in an operational context under very good conditions (large data sets – i.e. >30 images, dense PS network, quasi linear deformation regimes), the precision could reach 0.5 mm/y for the annual deformation rate and 3 mm for the displacement values at given acquisition dates for PSI based on data from ERS, Envisat/ASAR or equivalent (C-band, resolution ~10m, repetitiveness of ~ 1 month). However, in less favourable cases (deformation rates higher than some cm/y, sparse PS, non-linear deformation) results could be worse. Studies based on inter-comparison of different PSI techniques and validation respect to ground measurements (see for instance Raucoules et al. 2009) showed that in unfavorable cases, the precision value can drop to 1.5 mm/y and the accuracy can be much worse (>5 mm/y). Furthermore, deformation superior to ~cm/y tends to be under-estimated if no prior assumption on the deformation is used in the processing (Raucoules et al., 2009). This issue is not expected for CO₂ storage applications as shown by the estimates of ground displacements resulting from a typical CO₂ injection scenario (see Figure 1B).

On this basis, a detection threshold for an individual deformation value of 5 mm (i.e. below which the deformation phenomenon is very unlikely to be detected) is considered in the present study. For the considered injection case in section 1.3, we show that deformation phenomenon associated with the CO₂ injection is likely to be detected only after the first year

of injection. Different injection scenarios are then considered with injection rates and depths respectively ranging from 0.5 to 2.5 Mt/y and 1000 to 2500 m and assuming the aquifer formation properties constant as described in Table 1. Figure 3A) shows the maximum vertical displacement reached at surface in the injector near-zone after respectively 1 and 10 years of injection (top and bottom left panels). Several aspects can be outlined:

- The maximal vertical displacements is proportional to the mass injection rates, whereas it is non-linear with depth mainly due to the non-linear form of the relationship between the fluid properties of CO₂ and brine with depth;
- The depth of the aquifer storage formation by 500m implies increasing the necessary injection rate by 0.5 Mt/y for the surface deformation to be detectable. For instance, ground displacements after 1 year caused by CO₂ injection at 0.5Mt/y within a 1000m deep aquifer is equivalently detectable as those caused by CO₂ injection at 1.0 Mt/y within a 1500m deep aquifer;
- For the whole range of depths and time durations, the deformation associated with the 0.5 Mt/y injection scenario is hardly detectable ;
- Only the deformation associated with the 1000m deep injection may be detectable over the whole range of injection rates.

[Figure 3 about here]

2.2. Spatial scale

The basic idea of PSI techniques is that there exist points with stable backscatter characteristics during the period covered by the data series. In other terms, those points (or PS) have high (respect to other pixels of the images) backscattered amplitude that does not change significantly from one image to other. They are generally considered as objects with extents smaller than the pixels where they are located. Such PS are little affected by geometric

and temporal decorrelation and allow (using statistical criteria) to compensate the atmospheric phase screens in order to improve the precision of the measurement. In urban area, buildings and other man-made structures often act as PS due to their corner reflector-like scattering behavior and high radar reflectivity so that we can obtain a very high density (hundreds per km²) of PS, even exceeding thousands per km² in arid regions (e.g., Bell et al., 2008).

However, the total area at ground surface to be affected by the deformation phenomenon caused by CO₂ injection at depth is expected to be very large in relation with the large overpressurized zone at depth. Several authors have recently shown that the latter can reach of the order of several to more than a few tens of kilometers (e.g. Birkholzer et al., 2009). The detectable zone of deformation at surface will then be characterized by a lateral extent of the order of a few kilometers in the early stage of injection (ranging between 0.5 and less than 5 km after 1 year of injection, Figure 3B, top) and of more than ten of kilometers (ranging between ~5 km and less than 15 km after 10 years of injection, Figure 3B, bottom). Such a large size of the monitored area implies that the size of the area covered by the satellite acquisitions (i.e. swath) should ideally be larger than 50 km. Yet, the larger the swath, the lower the resolution of the sensor. For instance, TerraSAR-X (mode scanSAR) presents a very large swath of 100km, but with a resolution of ~16m, which may be insufficient (see discussion below in section 2.3 and 2.4). Conversely, very high resolution sensors (~1m, such as TerraSAR-X or Cosmo-Skymed) offer insufficient coverage (~10km) and their use implies acquiring and processing a much larger amount of image data, which may become cost and resource intensive.

Furthermore, over such large areas, we can reasonably expect a vegetated cover (fields, forests, etc.) on a significant part of the storage site. For illustration purpose, the PICOREF sector in the Paris basin (of 3,455 km², see location in Figure 6), where the potential implementation of CO₂ storage sites have been investigated (e.g. Grataloup et al., 2008), is

characterized by a land use composed of less than 5 % of artificial / urban areas and more than 95 % of natural (mainly forests) and agricultural areas. In such natural terrains, the absence of bright man-made structures might lead to sparse PS network (with density ~ 10 PS every km^2 to less than $1/\text{km}^2$). This constitutes a major obstacle to the phase unwrapping stage, where the solutions are directly dependent on the PS density and makes reliable estimation of deformation using PS techniques a challenging task.

The use of L-band data may contribute to improve the processing given that the vegetation is better penetrated using signal with short wavelength (e.g. Raucoules et al., 2007). Unfortunately there is currently, to the authors' knowledge, (and probably for the next 2 decades) no planned satellite mission fulfilling the requirements in terms of resolution and/or acquisition repetitiveness for the proposed monitoring application as discussed below.

2.3. Temporal scales

CO_2 injection operations are typically planned to last between 25 and 50 years. This “long term” monitoring implies considering several issues.

A first difficulty is the availability of a space-borne sensor, whose mission durations are typically of the order of a ten of years (e.g. see Hanssen, 2005, Table 2). Thus, any long term monitoring of the injection operations should be designed potentially considering a minimum of 2 to 3 satellites, whose characteristics (orientation of the orbital trajectory, center frequency, C-, L- band, etc.) might change from a satellite to another and not be necessarily suited for interferometric analysis. For instance, the currently-used ENVISAT mission, which was deeply modified in October 2010 (change in the orbital characteristics, affecting the possibility of carrying out reliable PSI processing after this event), will come to an end in the coming years. A transition period with another space-borne sensor should be accounted for in the design of long term monitoring plan. For instance, the successor of ENVISAT, namely Sentinel 1, is to be launched in 2013. This 7-12 years mission will consist in a space-borne

SAR in C-band (and therefore providing data similar to ASAR) with a repetitiveness of 12 days. Considering an ideal data-set for PSI baseline of >30 images the transition period should last ~10 months, i.e. before the planned commercial-scale deployment of storage sites by 2020 (IEA, 2009).

A second difficulty arises from the decorrelation of PS over time, i.e. the “life expectancy” of the PS over such long time durations. Ferreti et al. (2003) tackled this issue by identifying points corresponding to PS only on sub-sets of the full ESA-ERS data set over the period 1992-2003 on the Milano urban area. This consisted in identifying PS, which have appeared or have disappeared during a given time span between the first and last acquisition. The number of such points is usually 10% of the number of PS over a period of a ten of years. This can be considered an order of magnitude of the life expectancy of a PS.

Though requiring further investigations, the effect of the land cover nature (urban / rural) is expected to have little influence on the life expectancy of PS. It is true that on vegetated area the temporal decorrelation (on none-PS points) is globally higher than on urban areas, but pure point target PS are little affected by temporal decorrelation (as they are identified by the temporal stability of their signal) whatever on urban and on non-urban areas.

The use of high resolution data is expected to improve the life expectancy of PS. As shown by Crosetto et al. (2010), higher PS densities are expected with higher resolution sensors. Assuming an equivalent PS decay rate for different resolutions, the total number of PS is expected to be larger with high resolution sensors considering an isolated small area with high PS density located in a larger area depleted of PS (e.g. small groups of buildings in a larger agricultural zone). Following this reasoning, the probability of having at least a few PS lasting during the whole observation period is therefore higher with high resolution sensors (provided that a maximum of isolated building groups will keep some PS during the observation period). Yet, as mentioned in section 2.2, the high resolution requirement is limited by the

large swath requirement. Current sensor TerraSAR-X (Strip Map Mode) and future Sentinel-1 mission should both fulfill such a trade-off, but with major differences in the data provision policy.

This latter issue should be carefully accounted for, because long term monitoring possibly implies constituting a large data base (depending on the acquisition and processing frequency; which is further discussed in section 2.4). To remain cost-effective regarding ground-based geodetic measurement techniques (e.g., optical levelling, GPS, tiltmeters, etc.), a possible strategy can be similar to the provision policy associated to the Global Monitoring for Environment and Security (<http://www.gmes.info/>), which allows obtaining the data at low price as envisaged for the future Sentinel-1 mission. The interested reader can refer to (Rucci et al., 2012) for additional discussions on the use of future Sentinel-1 and new X-band sensors for reservoir applications.

2.4. Spatio- temporal evolution

The monitoring of CO₂ storage sites has two major objectives (see e.g., Benson, 2006). A first objective, categorized as “verification”, focuses on the monitoring of the expected behaviour of the storage complex, in particular detecting the location and quantifying the size of CO₂ plume within the reservoir and tracking the pressure front propagation. The second objective, categorized as “early-warning”, focuses on the detection of any “abnormal behaviour”, i.e. deviations from the expected behaviour of the storage complex. This latter case corresponds to the occurrence of unwanted events such as the sudden (i.e. over a short time span) multi-millimetric uplift localized on a fault zone, which may be related to the fault reactivation at depth (see e.g., Rutqvist et al., 2010).

Regarding the “verification” objective, the acquisition and processing rate should be chosen based on the simulations of the expected spatio- temporal evolution of the deformation phenomenon. In this view, section 1 provides useful orders of magnitude for a typical

injection scenario. At a given location, Figure 2 shows that the deformation phenomenon is characterized by a highly non-linear evolution over time. This might limit the performance, because the PSI technique is generally better applied for rather conservative types of deformation (e.g. Hanssen, 2005), e.g., characterized with (approximately) uniform deformation velocity relatively linear temporal evolution of deformation velocity or periodic (such as seasonal natural gas storage, Teatini et al., 2011). To tackle this issue, an alternative would be to focus on the discrepancies of the measured displacement field respect to the proposed evolution model, i.e. deviation to the predictive model. By subtracting the model-based simulation of the phase to the interferometric data, an important part of the (non-linear) temporal signal would be removed, facilitating the PSI processing (in particular by reducing the risk of unwrapping errors). Besides, the important information is the (unforeseen) discrepancy respect to the model that is needed for adjusting the representation of the phenomenon. The proposed iterative procedure described in section 3.3 that revisits periodically the knowledge of the phenomenon, could partly deal with this issue.

Figure 1B provides information on the spatio- temporal evolution of the “deformation front” given a typical injection scenario (see details in section 1.2). An individual measurement point located at a given lateral distance from the injection zone, requires a major and more frequently sampled monitoring during a specific period of the order of ~2-4 years, the beginning of this period depending on the distance to the injector. In other terms, a “deformation front”, as schematically depicted in Figure 4, affects the location during this short time span $\Delta t=2-4$ years. Before the front has passed no deformation affects the point. After, the point has smaller displacement (see Fig. 4). Such a spatio- temporal behaviour has implications on both the choice of the frequency of image data acquisition (i.e. sampling procedure) and of the processing rate (i.e. frequency of PSI analysis).

390 At a given location, the monitoring should be highly-rated sampled during the short period of
391 the deformation front passage. As indicated in section 2.1, >30 images is an ideal data set size
392 for precision reasons. The orbit cycle of ASAR-like sensors (about 10 acquisitions per year)
393 may be therefore insufficient to carry out such a measurement at the limit of the sensitivity of
394 the method. Current sensor TerraSAR-X (Strip Map Mode) and future Sentinel-1 mission
395 should fulfill such a requirement (with both repetitiveness of the order of a ten of days), but
396 with differences in the data provision policy (see section 2.3).

397 Besides, changes in the velocities values of the differential displacements are expected to be
398 detectable only after a few months (except for the case of multi- millimetric sudden ground
399 movements, which is discussed in the following). The processing of the data image with very
400 high frequency (e.g. every day) may not be appropriate given the described physical evolution
401 of the deformation, but also considering cost and resource constraints. Considering the
402 expected spatio- temporal evolution of the deformation phenomenon as calculated for the
403 typical injection scenario described in the section 1.2, one PSI analyse every 3 – 6 months can
404 be proposed to fulfil the “verification” objective of monitoring. Noteworthy, this processing
405 rate is intermediate between quasi- real time (e.g. bottom-hole fluid pressure) and pluri-
406 annual monitoring techniques (e.g. seismic campaign).

407 Regarding the “early- warning” objective of the monitoring, two cases can be considered. On
408 the one hand, potential zones at risk (e.g. fault zones, injection zone, etc.) can be identified
409 prior the injection operations based on a risk assessment procedure (see Bouc et al., 2011). On
410 these localized zones, a specific PSI analysis can be envisaged using high resolution/high
411 repetitiveness (but reduced swath) data equivalent to those provided by the current X-band
412 sensors TerraSAR-X or COSMO-SkyMed (see e.g., Ferretti et al. 2011b), to complement the
413 PSI analysis for the “verification” monitoring. Noteworthy, other ground-based geodetic

techniques would require systematic on-site measurements, such an approach being time consuming and resource intensive.

On the other hand, if any “abnormal behavior” is detected in an “un-expected” zone either after processing the image data or based on other indicators (induced seismicity recorded at the surface due to possible fault reactivation; increase of the fluid pressure recorded in the monitoring aquifer indicating a possible leakage, etc.), the considerations for data acquisition and processing rate as discussed for the verification monitoring should be adjusted. The great advantage of PSI analysis compared to ground-based geodetic measurement is the possibility to assess deformation after the unwanted event has occurred, because image data would have been archived without user’s intervention (e.g., every 12 days using the future Sentinel-1 sensor). Punctual and local studies on short time spans can also be proposed to focus on the “un-expected” zone at risk to complement the PSI analysis for the verification monitoring.

[Figure 4 about here]

3. Planning a network of artificial reflectors

3.1. Description of corner reflector devices

One major difficulty to the implementation of PSI in the CO₂ storage context stems from the potentially low PS density over such large areas as previously discussed. Though improved co-registration and use of more efficient computational techniques (the interested reader can refer to Sousa et al., 2011) can provide valuable support, a potential solution to enhance the performance in regions where bright man-made structures are merely absent can rely on the installation of artificial PS, i.e. corner reflectors CR (e.g., Novali et al., 2005). These artificial metallic devices (of generally trihedral or cubic geometry characterized by a few tens of centimeters long) are installed on ground providing high backscatter to the radar signal to

complement the existing “natural” PS network, i.e. to fill the gap between natural persistent reflectors. This approach has been proposed in other contexts (mine, volcano, coastland and marshland environments, etc.), where the ground movements’ detection has proved to be very challenging. See for instance the recent application case in the Venice lagoon (Teatini et al., 2010).

3.2. Optimizing the position of the CR

To the authors’ knowledge, very few works have handled the issue of planning the position of CR in a predictive fashion, i.e. before any ground deformation measurement has been carried out. For instance, in the recent interferometric analysis of the land subsidence in the Venice lagoon (Teatini et al., 2010), a network of 55 CR has been planned taking into account a fixed distance of 1 km between them of any adjacent natural reflectors. Yet, these were installed only once the full interferometric analysis had been carried out for a ten of years.

Planning the CR network using an “one-size-fits-all” approach, i.e. using a fixed distance value may rapidly become impracticable considering the large area expected at the end of injection (of ~325 km² after 25 years for the case modeled in section 1.3). Optimizing the location of the CR should result from a trade-off between the issues related to the installation of such devices (costs, authorizations, maintenance, etc.) and the requirements in terms of coverage and precision for the PSI results. Furthermore, the time-scales of CO₂ storage constitute a major constraint for the monitoring plan that should be designed to follow the long term evolution of the ground movement over a time span ranging from 25 to 50 years.

An example of a ground-based network, i.e. of devices fixed at the surface that exist over such a long time duration, is provided by the networks of benchmarks used for national spatial reference systems (e.g. in France, the currently-used network has been installed since the 19th century), but dimensions of such ground-based devices have nothing comparable to the ones of a CR.

In this context, a crude design approach based on the expected surface deformation calculated regarding the whole time duration of the storage project may be highly limited by both maintenance issues of the CR network given such large spatio-temporal scales and by the changes in the sensors characteristics (typically each 7-10 years, see section 2.2) over the full lifecycle of the storage injection phase. Therefore, we advocate a design strategy thought in an iterative fashion:

- *Step1*: estimate the expected spatio-temporal evolution of ground surface displacements induced by CO₂ injection operations at different epochs for the full period of injection. The duration of each epoch should be no longer than a ten of years to handle the possible change in the sensors characteristics. Let us consider the estimates of the surface deformation after 5 epochs of 10 years each. This step should be based on large-scale geomechanical analysis of the complex site. This can rely on analytical models such as the multilayered visco-elastic solution developed by Fokker and Orlic (2006) or in a first approach, the one described in section 1 presenting the attractive feature of a rapid estimation, but limited by the simplifications inherent to the analytical nature of the model of such a simplified model (as discussed in section 1.3). A more sophisticated analysis can rely on large-scale coupled numerical models as demonstrated by Rutqvist et al. (2010) in the In Salah's context. The advantage of such analysis are the ability to take into account complex injection scenarios, complex reservoir pore pressure spatio-temporal evolution, complex geological structures (e.g., multi-layered system as present in sedimentary basin suitable for CO₂ storage, Birkholzer et al., 2009;
- *Step2*: based on the expected extent of detectable deformation surface, localize the a priori good candidate for PS, i.e. spatial points that appear to be persistent in the

present, but above all, that shall remain persistent over the full duration of the injection. Long term “natural” PS can constitute man-made structures within urban zones (historical monuments, churches, industrial plants, roads, etc.). We can consider that a large number of these spatial points identified as PS will keep their characteristics (reflectivity) over the time duration of the considered epoch (of a ten of years). This assumption can be considered valid regarding the study of Ferreti et al. (2003), as discussed in section 2.2.⇨

- *Step3*: optimize the position of the corner reflectors CR considering the expected detectable surface deformation for the whole duration of the injection. We advocate choosing the distance between CR and natural PS based on a criterion dependent on the initial network of natural PS. The idea is to maximize the spatial coverage of the area where ground deformation is expected to be detected considering the location of identified potential “natural” PS. Formally, this can be achieved by treating the “natural” persistent scatters as Voronoi sites and by affecting to each of them a Dirichlet cell (also named Voronoi cell) consisting of all points closer to PS than to any other site as schematically depicted in Figure 6A. The segments of Voronoi cell are all the points in the space that are equidistant to the two nearest sites PS. The potential positions of the CR are then chosen as the Voronoi nodes corresponding to the equidistant to three (or more) PS sites. The positions of the CR merely derive from a pure mathematical space-filling criterion, but in real-case applications, adjustments will certainly be necessary if the Voronoi-based method indicates installing the CR in densely vegetated cover (forests, wetlands, etc.), which may highly prevent the detection or the installation of the CR, or too close to another CR (e.g., with a distance <1 km). Then, the CR only lying within the expected detectable zone for the

considered 10-years epoch, can be selected. These CR should be installed to help monitoring the expected surface deformation over the duration of one epoch.

Based on the discussions in section 2, the PSI analysis to fulfil the “verification” objective of the monitoring can be conducted using data characterized by a large swath, a rather good resolution and repetitiveness of a ten of days. The processing rate of the image data should be chosen depending on the simulation predictions for the spatio-temporal evolution of the deformation phenomenon associated with CO₂ injection. The simulations for the typical injections scenario (section 1.2) show that a processing of 3-6 months can be envisaged during the 10-year epoch. This rate can be adjusted especially depending on the detection of a sudden “abnormal behaviour” on a localized zone (e.g., sudden multi-millimetric uplift due to possible fault reactivation). A complementary PSI analysis using high resolution / high repetitiveness (but reduced swath) data can be proposed on these zones at risk (see discussion in section 2.4). Such an iterative approach allows a frequent re-interpretation of the discrepancies between model and measurements in terms of evolution predictions (i.e. deviation to the predictive model). Valuable information on the storage complex behaviour can be extracted in an inversion procedure as proposed more specifically in the field of CO₂ storage by Vasco et al. (2008a&b). The combination of both information (correction of the model based on the measurements and inversion of the complex behavior) can serve to increase the quality and robustness of the predictions.

The procedure is then repeated for the next 10-years epochs (step 1). Using the initial PS network enriched with the CR identified for the previous epoch (step 2), the next CR (i.e. necessary for monitoring the next epoch) can be identified using the updated expected detectable surface deformation region (step 3), and the procedure is then repeated.

~~Noteworthy,~~ Before the end of each 10-years observation epoch, a transition period should be envisaged between two successive satellite missions, with sensors of possibly different

characteristics. During this period, a sufficient amount of SAR data (> 30 images) should be acquired for the PSI baseline using the new sensor. Considering a repetitiveness of a ten of days, this period should last ~1 year. Figure 5 summarizes the sequence of the steps considering two epochs and two different sensors.

[Figure 5 about here]

In case of sensors with different characteristics, a change in the configurations (e.g. orientation) of the CR, which have been installed during the first epoch, should be envisaged to make these CR “visible” by the new sensor. In such a case, a gap in the produced deformation time series may be expected of the order of few months, but only partly on the ground surface covered by the SAR data, i.e. corresponding to the region whose CR were adapted to the first 10-years epoch. To the authors’ knowledge, the transition between two sensors during the implementation of SAR interferometry combined with CR has not been experienced yet and requires further investigations.

Finally, considering such a long term monitoring, the possibility that during certain periods, the lack of satellite mission with suitable characteristics cannot be fully discarded. In such a case, the information provided before and after the information gap could still provide useful information on the evolution of the injection processes.

3.3. Application to a potential storage site in the Paris basin

To illustrate the main steps of the proposed methodology, we apply the described methodology to a potential injection site selected within the PICOREF sector in the Paris basin (Figure 6). This potential storage site was identified based on the combination of criteria in terms of capacities and injectivity, environmental constraints, existing land-use and underground-use, economic and social aspects and based on a comprehensive risks analysis (Grataloup et al., 2008; Bouc et al., 2011). Figure 6 shows the location of the potential injection well (outlined by a red cross marker). We consider 40 years of CO₂ injection at a

rate of 2 Mt/y into the 1500m deep carbonate aquifer of the Dogger formation. The aquifer properties are: intrinsic permeability of 1.10^{-13} m²; porosity of 12 %; Young's modulus of 24 GPa; Poisson's ratio of 0.29 (Rohmer and Seyedi, 2010 and references therein).

[Figure 6 about here]

- *Step 1:* in this example, the analytical model described in section 1 is used to estimate the lateral extent of the expected detectable zone of vertical displacements (considering a 5 mm detection threshold) induced by a whole CO₂ injection duration of 40 years and considering four 10-years long epochs. The final zone represented by a black circle in Figure 6 covers a total area of ~220 km² and corresponds to the zone of maximum extent that should be monitored by the PSI technique over the whole life span of the potential storage site;
- *Step 2:* we consider each centroids of the urban zone present within the detectable zone for the whole injection duration (total number of 24 zones). These represent localized zones where good candidates for natural PS are highly likely to be detected. In a preliminary approach, we only consider these centroids as natural PS (outlined in Figure 7 as pink diamond markers);
- *Step 3:* on this basis, we assign to each of the centroids a Voronoi cell (Figure 7A) and choose the potential CR as the Voronoi cells (outlined in Figure 7A as blue triangular markers); the CR lying within forest zones or distant from each other of less than 1km are detected and are re- adjusted (deleted or re-localized). A total number of 23 CR are in this manner identified within the detectable region for the whole duration of the injection (here 40 years, black -coloured circle in Figure 7B).

[Figure 7 about here]

Using the region of detectable deformation for the first 10 years of injection (light grey-coloured circle in Figure 7B), a total of 6 CR are identified through the Voronoi analysis.

Among the identified CR, two CR should be re-localized, because they lie within forest areas and one CR should be deleted, because it is too close from the others. Without any other consideration (such as legal issues, accessibility of the site, ...), we are able to propose a monitoring procedure adapted to the expected characteristics of the deformation for the first 10 years of injection both based on CR-InSAR and on current PSI techniques. For the next 10-years epoch, Figure 8 provides an illustration of the location of the corresponding CR (i.e. after 10 years of injection) using the original PS network (Figure 7A, pink coloured diamond markers) enriched with the 5 CR selected for the first 10-years epoch. The expected detectable regions for the whole injection duration (at 20, 30 and 40 years) are then re-estimated (step 1), here assumed unchanged for illustration purposes. On this basis, the CR for the whole duration are identified (step 2 & 3). Then, using the expected detectable deformation region for the next 10-years epoch (here for the date 20 years), the CR for this epoch are selected (Figure 8B).

[Figure 8 about here]

4. Concluding remarks and recommendations

The present paper proposes a description of the characteristics of the surface deformation, which will be expected during the injection of CO₂ into deep aquifers during 25 – 50 years. On this basis, the associated constraints for the planning of a monitoring plan relying on PSI techniques are discussed. To overcome such limitations, we focused on the optimisation of a CR (corner reflectors) network. An iterative strategy is proposed, which is justified by the large spatial extent of the expected detectable region and by the changes in the sensors characteristics (typically each 7-10 years) that could result in a need of re-organisation of the network (and even CR characteristics such as orientation). At each period (say, every 10 years), the number and location of the CR, necessary for the monitoring of the surface

deformation of the next epoch, are estimated based on the prediction of surface deformation using large-scale geomechanical models. Furthermore, we propose to focus on discrepancies between model and measurements, which can be useful in terms of evolution predictions. To fulfil the “verification” objective of the monitoring, the PSI analysis should be frequently conducted during each epoch with a processing rate, which should be chosen depending on the predicted spatio- temporal evolution of the deformation phenomenon. The simulation results for a typical injection scenario show that a processing rate of the order of a few months may be sufficient. Such a frequent re-examination of the situation and model correction is therefore useful in a perspective of forecasting consequences of the injection. To fulfil the “early-warning” objective of the monitoring, a complement should be envisaged so that well definite zones at risk (such as fault zones) should be monitored using high repetitiveness / high resolution (but reduced swath) data. In both cases, a careful attention should be paid to cost and resource issues especially regarding provision policies of image data.

Finally, from now to the start of injection and during the 50 years injection, improvement of PSI processing techniques can occur. For instance, Ferretti et al. (2011a), recently proposed a technique (SqueeSARTM) based on the concept of diffuse scatterers, which can improve considerably the density of usable “natural” scatterers on certain un-urbanised area. See the recent application of such a technique at In-Salah (Rucci et al., 2012). If such improvement is efficient for surface characteristics such as those existing on the monitored area, an optimisation of the network could be proposed – probably based on a reduced CR number.

The periodic re-thought of the CR network will therefore allow the possibility of methodological improvement in addition to taking into account new sensors characteristics.

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Appendix A: General solution to ground displacements

Segall and co-authors (Segall, 1992; Segall and Fitzgerald, 1998) have presented poro-elastic solutions for stress and displacement fields estimate in an elastic half-space, induced by fluid extraction (or injection, the solutions being merely the opposite) for general axi-symmetric geometries with arbitrary pressure radial distribution within the reservoir (given as a function of space and time for instance from field data and/or reservoir simulations). Noteworthy this solution provides both horizontal and vertical surface displacements, but we will focus on the latter one.

The variation in reservoir pore pressure p is assumed to mainly govern the volumetric strain in the reservoir. The vertical displacement at the radial distance r at the free surface $u_z(r)$ results from the cumulative contribution of all the rings of dilatation at radius $\tilde{r}$ and depth Z (as schematically depicted in Figure 9), the magnitude of dilation being proportional to the product of the pressure p and of the Biot's coefficient b . Based on the Green's function at the free surface $g_z(r)$ for the radially symmetric case (Equation A1b), the solution for $u_z(r)$ holds as follows:

$$u_z(r) = \frac{b \cdot 2(1+\nu)}{E} \int_0^{\infty} \int_0^{\infty} p(\tilde{r}, Z) \cdot g_z(r, z, \tilde{r}, Z) d\tilde{r} dZ \quad (\text{A1})$$

where:

$$g_z(r) = (1 - 2 \cdot \nu) \cdot \tilde{r} \cdot \frac{Z \cdot K^3 \cdot F(K)}{4\pi \cdot (1 - K^2) \cdot (\tilde{r} \cdot r)^{3/2}} \quad (A2)$$

where:

$$K^2 = 4 \cdot r \cdot \tilde{r} / (\tilde{r} + r)^2 + Z^2 \quad \text{and } F(K) \text{ is the complete elliptic integral of the second kind.}$$

The physical properties are described in Table 1.

[Figure 9 about here]

Appendix B: General solution to the pressure build-up

The radial pore pressure $p(r, t)$ evolution (Equation B1) is assessed based on the analytical solution developed by Mathias et al. (2009a) using the method of matched asymptotic expansions for the non-inertial flow of CO₂ into a slightly compressible brine aquifer (assumed to be an open system, and the pressure corresponds to the initial one) with a vertical pressure equilibrium assumption. This solution holds as follows, distinguishing three zones:

- the CO₂ fully saturated zone (near the injector), for $x \leq 2\gamma$ (x being dependent on r , see Eq. B2 and γ is the ratio of the viscosity of CO₂ μ_{CO_2} to the one of the brine μ_{brine});
- the diphasic zone (brine + CO₂), for $2\gamma \leq x \leq 2/\gamma$;
- the brine-filled zone in the far field for $2/\gamma \leq x$.

$$\begin{aligned}
p(x,t) = & \frac{1}{2\gamma} Ei\left(\frac{\alpha \cdot x}{4 \cdot \gamma}\right) + \frac{1}{2\gamma} \left(\ln\left(\frac{\alpha \cdot x}{4 \cdot \gamma}\right) + \kappa \right) \\
& + \begin{cases} -\frac{1}{2} \ln\left(\frac{x}{2 \cdot \gamma}\right) - 1 + \frac{1}{\gamma} - \frac{1}{\gamma} \left(\ln\left(\frac{\alpha}{2 \cdot \gamma^2}\right) + \kappa \right) & \text{if } x \leq 2\gamma \\ -\left(\frac{x}{2 \cdot \gamma}\right)^{0.5} + \frac{1}{\gamma} - \frac{1}{2\gamma} \left(\ln\left(\frac{\alpha}{2 \cdot \gamma^2}\right) + \kappa \right) & \text{if } 2\gamma \leq x \leq 2/\gamma \\ -\frac{1}{2\gamma} \left(\ln\left(\frac{\alpha \cdot x}{2 \cdot \gamma}\right) + \kappa \right) & \text{if } x \geq 2/\gamma \end{cases}
\end{aligned}
\tag{B1}$$

where:

$$\begin{aligned}
x = & \frac{(r/r_w)^2}{t \cdot Q_w / (2\pi \cdot \omega \cdot H \cdot (r_w)^2 \cdot \rho_{CO_2})} \\
\alpha = & \frac{Q_w \cdot \mu_{CO_2} \cdot (c_{rock} + c_{brine})}{2\pi \cdot H \cdot k}
\end{aligned}
\tag{B2}$$

where:

$\kappa \approx 0.5772$ is Euler-Mascheroni constant ; r_w is the injector well radius (m); ρ_{CO_2} is the CO₂ density (kg/m³); Q_w is the mass injection rate (kg/s); t time (s); c_{brine} is the brine compressibility (Pa⁻¹); Other parameters are described in Table 1. Fluid properties are derived (viscosity, density and compressibility for both brine and CO₂) based on the empirical correlations with pressure and temperature supplied by Mathias et al. (2009b).

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Table caption

811

812 Table 1: Aquifer homogeneous properties used for the spatio- temporal analysis of the surface
813 vertical displacements

814

Aquifer property	Symbol	Value	Unit
Intrinsic permeability	k	$1.e^{-13}$	m^2
Porosity	ω	15	%
Thickness	H	50	m
Salinity	sal	150	g/l
Rock matrix compressibility	c_{rock}	$4.5e^{-10}$	Pa^{-1}
Young's modulus	E	15	GPa
Poisson's ratio	ν	0.25	-
Biot's coefficient	b	1.0	-

815

816

817 Table 2: Summary of the constraints on the implementation of the PSI technique and on the
818 sensor regarding the specificities of the deformation phenomenon associated with CO₂
819 injection at depth

Expected deformation characteristics	Corresponding constraints on the implementation of the PSI technique and on the sensor
Large spatial scales tens of km)	– Large swaths (>50 km) are required;
Large vegetated areas	– Poor PS density is expected. Additional Corner Reflectors could be required to complement “natural” PS network.
Long term monitoring (25 – 50 years)	– Because of limited sensors lifetimes, the use of different successive satellites is required; – High sensor repetitiveness (typically, ten of days or better)

	could reduce (respect to Envisat/ASAR-like configurations) the transition period between sensors by providing a minimum data archive to start the PSI processing (about 30 images) in the shortest possible duration; – Lifetime of PS are expected to be improved on small isolated areas with high density PS allowed by the use of high resolution image data; – Large amount of data are expected to be acquired, hence implying considering flexible and low-price data provision policies.
Spatio – temporal evolution of the deformation phenomenon	The acquisition and processing rate should be adapted to the expected spatio- temporal evolution of the deformation phenomenon. Based on simulations on a typical injection scenario: – the regions, where the deformation front passes, should be highly-rated sampled for a 2-4 years period; – the changes in the velocities values of the differential displacements are expected to be detectable only after a few months, implying a processing rate of 3 to 6 months.
Potentially sudden unexpected ground movements on localized areas	To fulfil the “early-warning” objective of the monitoring, a complement should be envisaged so that well definite zones at risk (such as fault zones) should be monitored using high repetitiveness / high resolution (but reduced swath) image data.

Figure captions

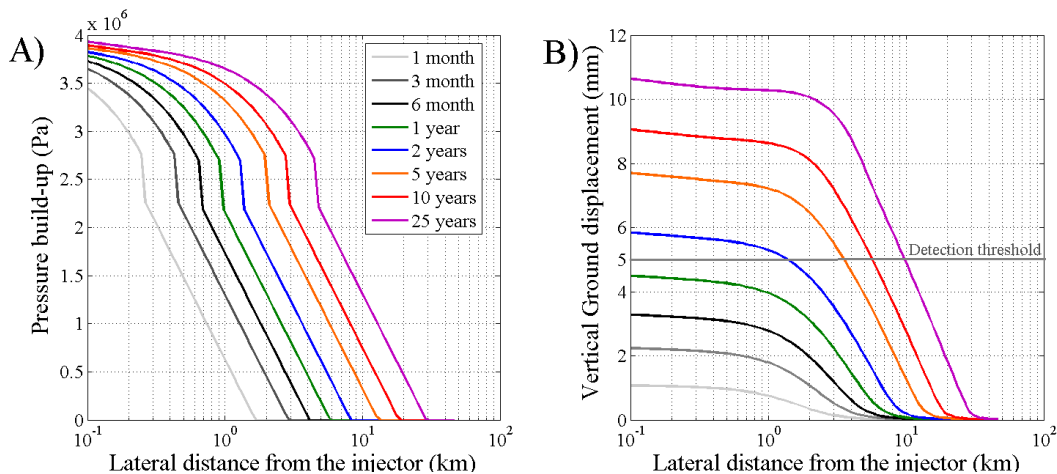


Figure 1: A) Pressure build-up (Pa) within the storage aquifer for a 1Mt/y CO₂ injection scenario into a 1500m deep aquifer (considering the aquifer properties in Table 1); B) Vertical displacement (mm) at the surface induced by the injection at depth. Detection threshold at 5 mm (discussed in section 2.1) is outlined by a grey-coloured horizontal line.

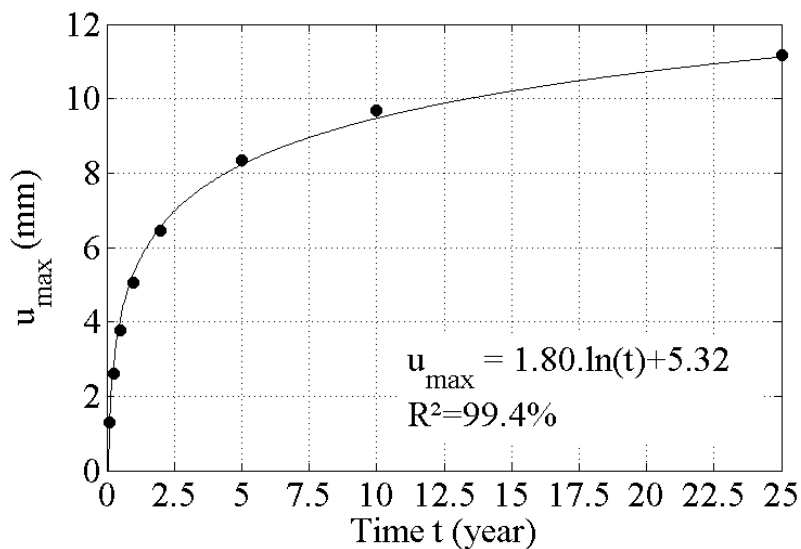
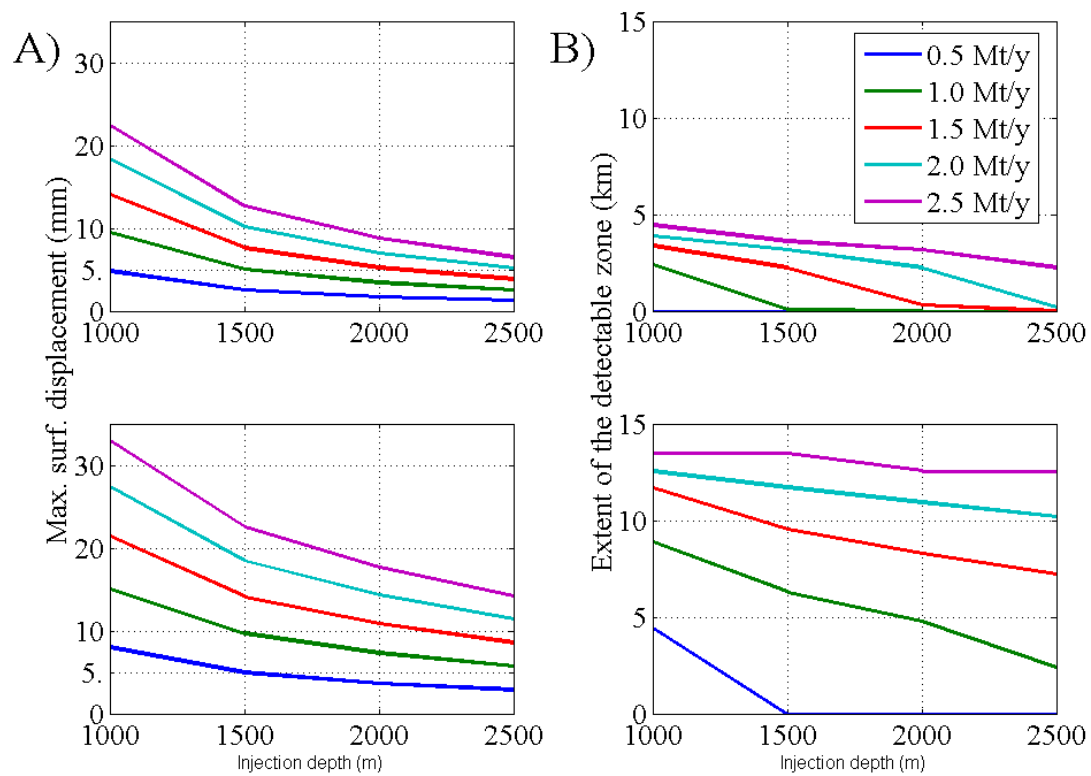
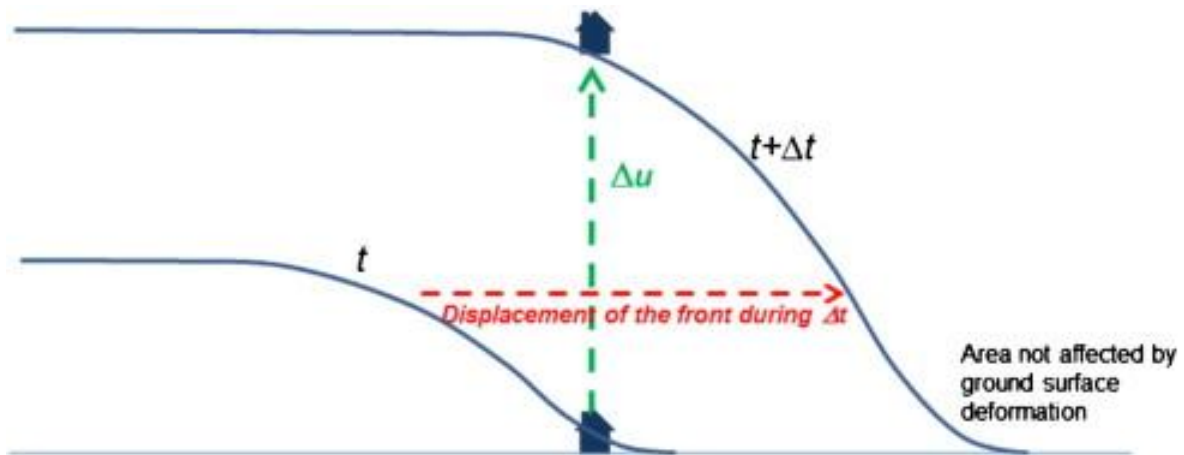


Figure 2: Temporal evolution of the maximum vertical displacement $u_{\max}$ (mm) within the injector zone for a 1Mt/y CO₂ injection scenario into a 1500m deep aquifer (considering the aquifer properties in Table 1).



830

831 Figure 3: A) Maximum vertical displacement reached at the surface respectively after 1 and
 832 10 years (top and bottom panels) considering different injection scenarios (mass injection
 833 rates and depths) and the aquifer properties described in Table 1; B) Corresponding lateral
 834 extent (km) of the detectable zone at the surface given a threshold of 5 mm respectively after
 835 1 and 10 years (top and bottom panels).



836

Figure 4: Schematic representation of the deformation to be measured. t corresponds to the beginning of the front pass on the measurement point, Δt the duration of the front pass. Δu is the resulting displacement on the observation point.

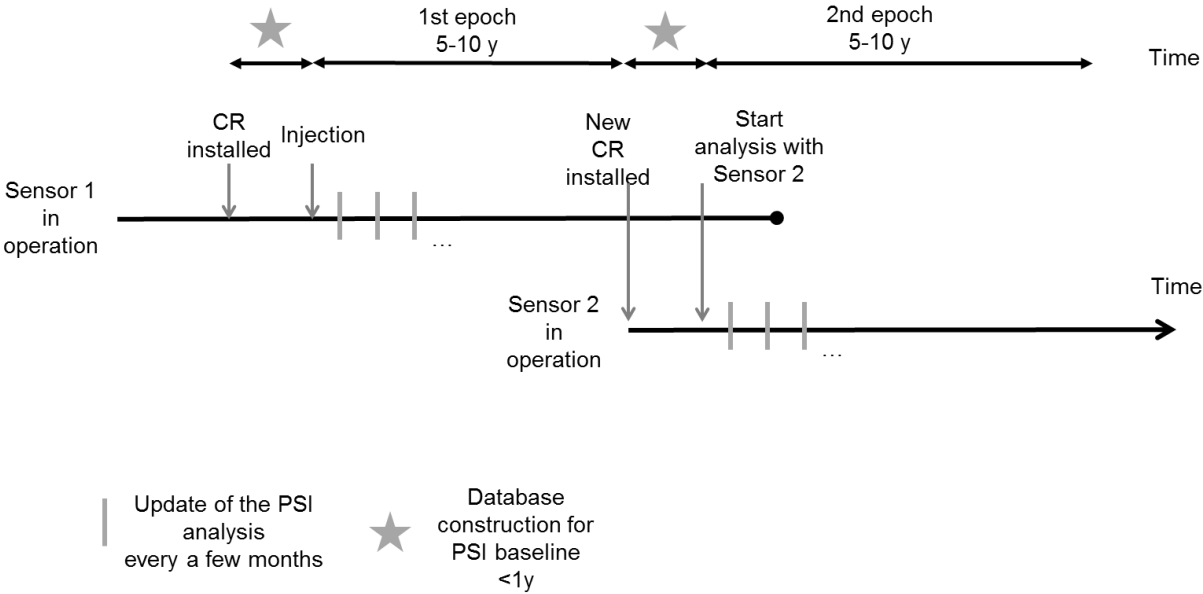
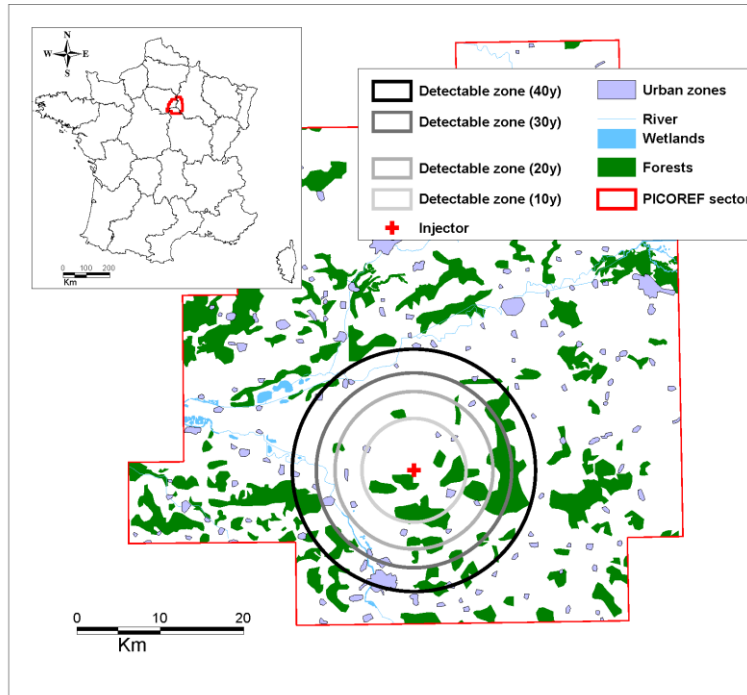
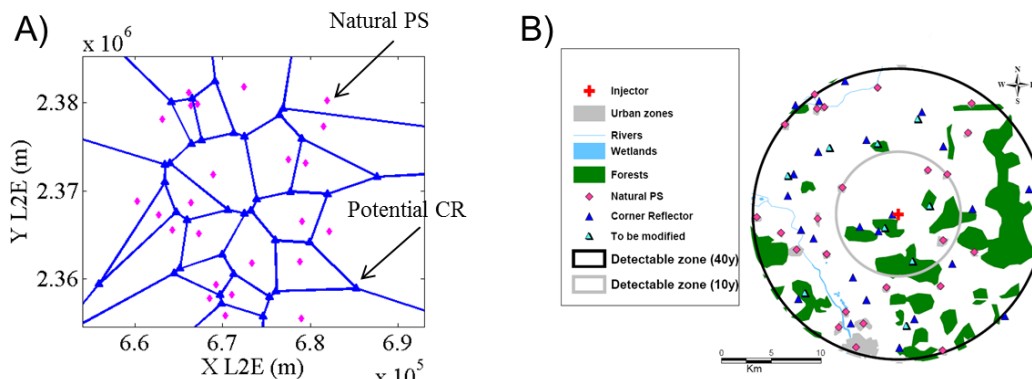


Figure 5: main steps for the application of the PSI analysis for “verification” monitoring using CR and considering the transition period between successive satellite mission (sensor 1 and 2 with possible different characteristics). The duration of the PSI baseline step (outlined by a star-like marker) is estimated considering a minimum of 30 images with a repetitiveness of a ten of days. The processing rate every a few months is estimated based on the spatio-temporal evolution of the deformation phenomenon associated with the typical injection scenario described in section 1.2. This should be adjusted in case of the detection of a “abnormal behaviour” (see discussion in section 2.4).



849

850 Figure 6: Location of the PICOREF sector (Grataloup et al. 2008) in the Paris basin context
 851 (red line). The red cross marker represents the potential injector position selected based on the
 852 risk analysis of Bouc et al. (2011). The circles represent the lateral extents of the expected
 853 detectable zones (5mm threshold) for different time durations considering a 2Mt/y injection
 854 scenario.



855

856 Figure 7: A) Voronoi analysis: pink coloured diamond markers represent natural PS located
 857 within the detectable zone expected for the whole duration of the injection (black circle, see
 858 right figure); blue coloured triangular markers represent potential CR at the edge of the
 859 Voronoi cells depicted by blue segments. B) Application to the PICOREF sector for the first

10-years epoch. Light blue coloured triangular markers outline the CR lying within forest zones or at a distance inferior to 1km to the neighbouring CR. Only the CR located within the area bounded by the light grey-coloured circle are integrated for the monitoring of the expected detectable zone for the first 10 years of injection.

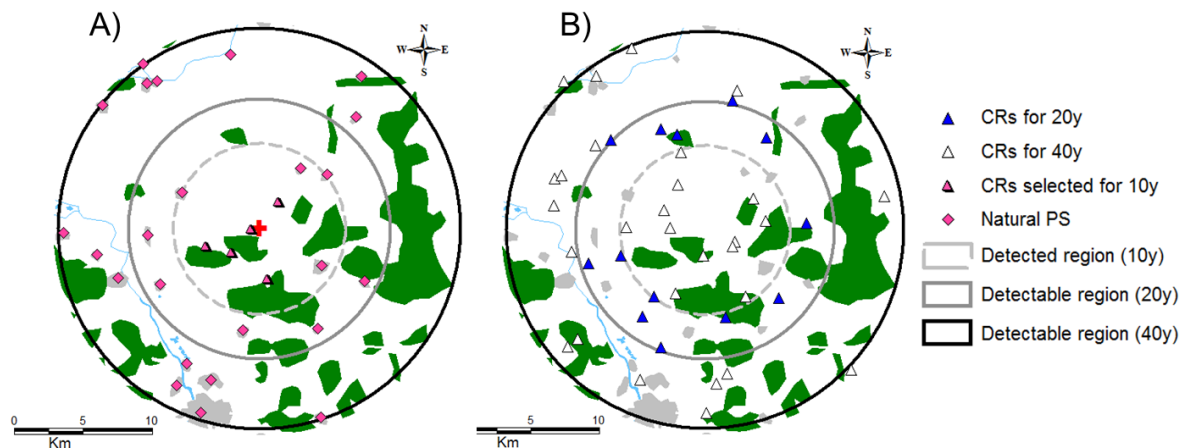
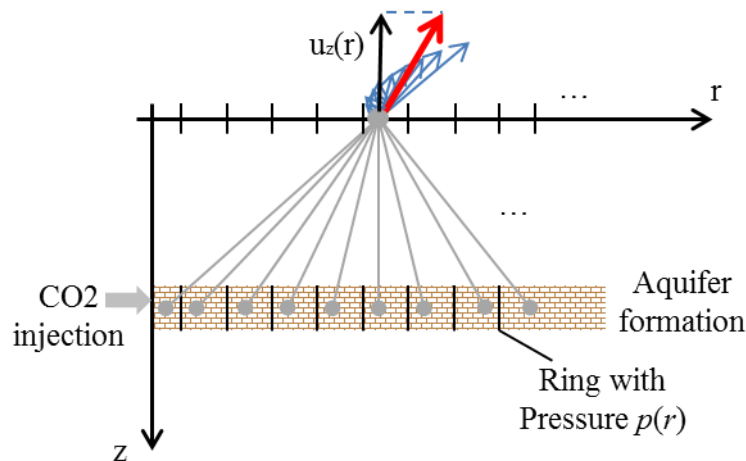


Figure 8: A) network of natural PS (pink coloured diamond markers) completed with the CR selected in the first 10-years epoch (pink coloured triangular markers); The dashed light grey coloured circle represents the detected surface deformation after 10 years of injection; The dark grey and black coloured circles respectively represent the expected detectable deformation regions after 20 and 40 years of injection. B) identification of the CR (blue coloured triangular markers) adapted for the monitoring of the next 10-years epoch (20 years) based on the CR identified for the whole injection duration of 40y (white triangular markers).



873 Figure 9: Schematic representation of the cumulative contribution (light blue coloured arrows)
874 of the rings of dilation with magnitude proportional to the reservoir pore pressure spatial
875 distribution $p(r)$ to the ground displacement (red arrow) at the lateral distance r . The vertical
876 ground displacement $u_z(r)$ is represented by a vertical black arrow.
877